

# Stabilization of Capacitated Matching Games

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## Cooperative Matching Games

In *Cooperative Matching Games* (CMG) we are given a graph  $G = (V, E)$  with edge weights  $w \in \mathbb{R}_{\geq 0}^E$  and vertex capacities  $c \in \mathbb{Z}_{\geq 0}^V$ . The vertices of the graph represent players. We call an allocation  $y \in \mathbb{R}_{\geq 0}^V$  *stable* if no coalition of players  $S \subseteq V$  has an incentive to deviate. This is described by the inequalities

$$\sum_{v \in S} y_v \geq \nu(G[S])$$

for all  $S \subseteq V$ , where  $G[S]$  is the subgraph of  $G$  induced by  $S$ , and  $\nu(G)$  is the value of a maximum-weight  $c$ -matching in  $G$ , formally defined as

$$\nu(G) := \max\{w^T x : x(\delta(v)) \leq c_v \forall v \in V, 0 \leq x \leq 1, x \in \mathbb{Z}\}.$$

The *core* of a CMG consists of all stable allocations of total value  $\nu(G)$ .

## Network Bargaining Games

In *Network Bargaining Games* (NBG) we are again given a triple  $(G, w, c)$ . The vertices of the graph represent players, the edges represent potential deals between players and the edge weights represent the values of the deals. Each player  $v$  can enter in at most  $c_v$  deals. For each deal, the involved players have to decide how to split the value of their deal. Hence, an *outcome* is naturally associated with a  $c$ -matching  $M$ , and a vector  $a \in \mathbb{R}_{\geq 0}^{2E}$  that satisfies  $a_{uv} + a_{vu} = w_{uv}$  if  $uv \in M$ , and  $a_{uv} = a_{vu} = 0$  otherwise. An outcome is *stable* if no pair of players has an incentive to break the current outcome to enter in a deal with each other.

## Equivalence and Counter Example

The value of a maximum-weight fractional  $c$ -matching, called  $\nu_f(G)$ , is defined as  $\nu(G)$  but without the integrality constraints. In unit-capacity graphs the following are equivalent: [7, 3]

- (1) the core is nonempty for CMG on  $G$ ,
- (2) there exists a stable outcome for NBG on  $G$ ,
- (3)  $\nu(G) = \nu_f(G)$  (we say  $G$  is *stable*).

This equivalence does not extend to capacitated graphs.

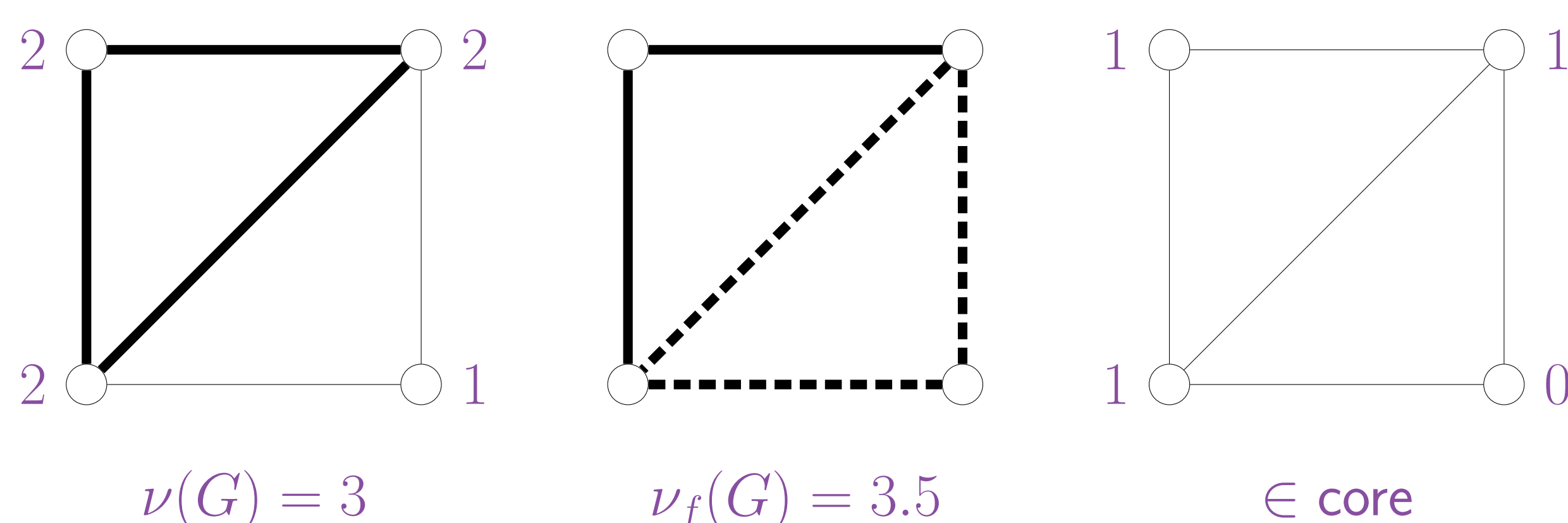
### Theorem 1

For a given triple  $(G, w, c)$  the following holds:

$$(2) \iff (3) \implies (1),$$

but (1)  $\not\Rightarrow$  (3) and hence (1)  $\not\Rightarrow$  (2).

[2] gives (2)  $\iff$  (3) and (3)  $\implies$  (1). The following example shows (1)  $\not\Rightarrow$  (3).



## Open Problems

- Computational complexity of deciding when the core of a CMG is nonempty in capacitated graphs.
- Studying other ways to stabilize instances.
- Studying the stabilization problem for other games defined on graphs.

## The Vertex-Stabilizer Problem

The vertex-stabilizer problem is motivated by the fact that not all graphs are stable. The goal is to minimally change a graph as to ensure a stable outcome. A natural way to change a graph is by removing vertices, i.e., blocking players.

**Vertex-stabilizer problem:** given a graph  $G$ , find a min-cardinality set  $S \subseteq V$  s.t.  $G \setminus S$  is stable.

A variation of the problem is the *M-vertex-stabilizer problem*, where the goal is to realize a given  $c$ -matching  $M$  as part of a stable outcome.

**M-Vertex-stabilizer problem:** given a graph  $G$ , find a min-cardinality set  $S \subseteq V$  s.t.  $G \setminus S$  is stable and  $M$  is a max-weight  $c$ -matching in  $G \setminus S$ .

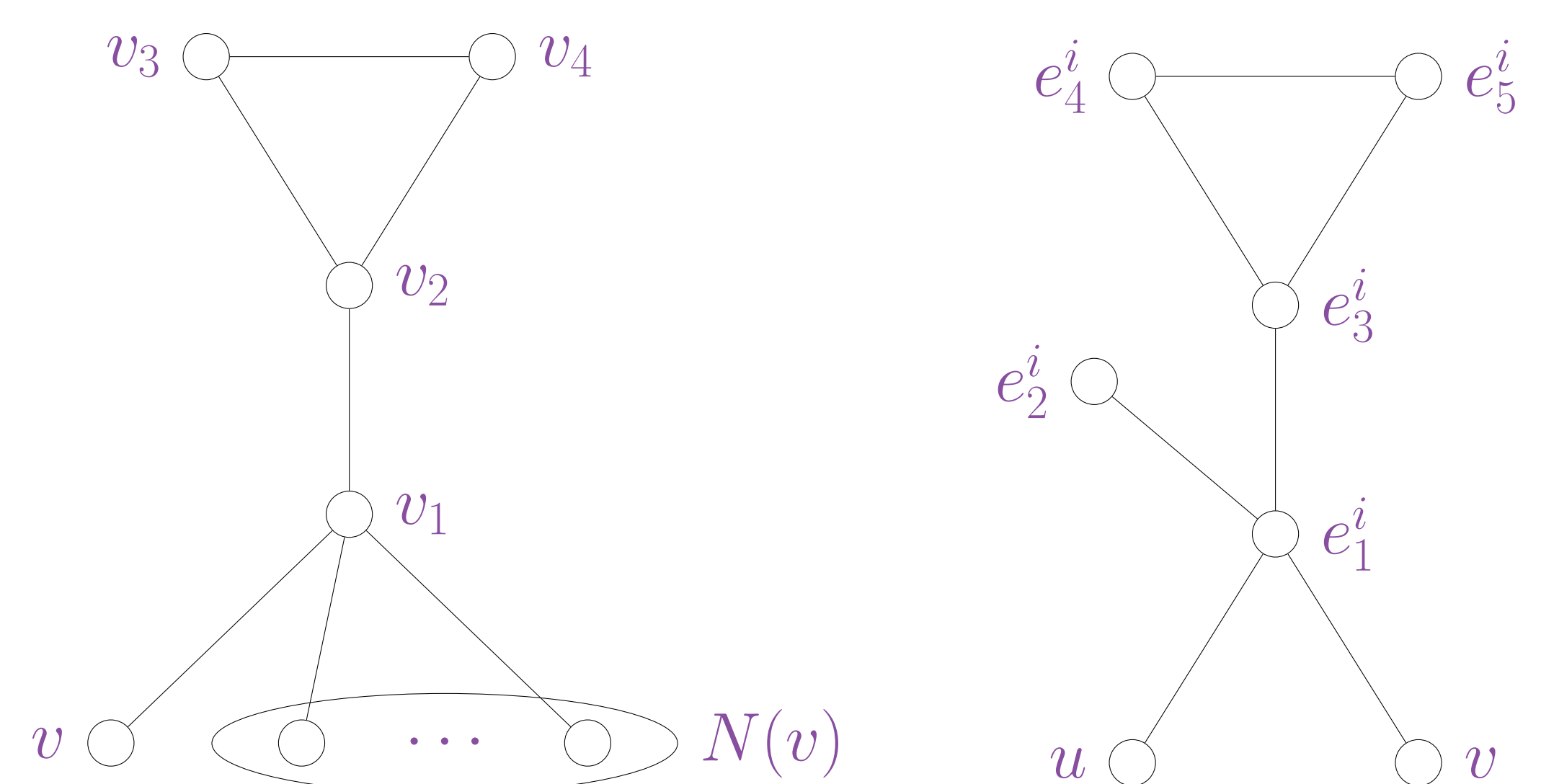
Both the vertex-stabilizer and *M-vertex-stabilizer problem* are polynomial-time solvable in unit-capacity graphs [1, 6, 8].

## Vertex-Stabilizer in Capacitated Graphs

### Theorem 2

Unless  $P = NP$ , the vertex-stabilizer problem cannot be approximated within a factor  $n^{1-\epsilon}$  for every  $\epsilon > 0$ , even if all edges have unit-weight.

This inapproximability result is obtained by a reduction from the minimum independent dominating set problem [5].



Note that an  $n$ -approximation exists, e.g., by removing all vertices (but two).

## M-Vertex-Stabilizer in Capacitated Graphs

### Theorem 3

The *M-vertex-stabilizer problem* can be solved in polynomial-time.

This result is based on combining a reduction from capacitated graphs to unit-capacity graphs from [4], and a careful extension of the algorithmic results for the unit-capacity *M-vertex-stabilizer problem* from [8].

## References

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